



Operating Instruction Manual
Generic Slave DTM for CANopen Slave Devices
Configuration of CANopen Slave Devices

Hilscher Gesellschaft für Systemautomation mbH

www.hilscher.com

DOC060203OI08EN | Revision 8 | English | 2017-03 | Released | Public

Table of Contents

1	INTRODUCTION.....	4
1.1	About this Manual	4
1.1.1	Online Help	4
1.1.2	List of Revisions	5
1.1.3	Conventions in this Manual	5
1.2	Legal Notes.....	6
1.3	Registered Trademarks.....	9
1.4	About Generic CANopen Slave DTM	10
1.4.1	Requirements	10
1.5	Dialog Structure of the Generic CANopen Slave DTM.....	11
1.5.1	General Device Information.....	11
1.5.2	Navigation Area	12
1.5.3	Dialog Panes	12
1.5.4	OK, Cancel, Apply and Help.....	13
1.5.5	Table Lines	13
1.5.6	Status Bar	14
2	GETTING STARTED.....	15
2.1	Configuration Steps.....	15
3	CONFIGURATION	17
3.1	Overview Configuration	17
3.2	Configuring Device Parameters.....	18
3.3	General Settings	19
3.3.1	Node ID, Device, Vendor.....	19
3.4	Special Function Objects.....	20
3.4.1	Synchronization Message	21
3.4.2	Time Stamp Message.....	22
3.4.3	Emergency Message.....	22
3.5	Object Dictionary.....	23
3.6	Process Data Objects.....	26
3.6.1	PDO Properties	26
3.6.2	PDO Mapping	29
4	DEVICE DESCRIPTION.....	31
4.1	Overview Device Description.....	31
4.2	Device.....	31
4.3	EDS	32
5	APPENDIX	33
5.1	COB-ID (Predefined Connection Set).....	33

5.2	User Rights	34
5.2.1	Configuration	34
5.3	References.....	34
5.4	List of Figures	35
5.5	List of Tables.....	35
5.6	Glossary.....	37
5.7	Contacts.....	38

1 Introduction

1.1 About this Manual

This manual provides information on how to set up CANopen Slave devices described with EDS files. These devices can be configured with the CANopen generic Slave DTM within an FDT Framework.

Dialog Panes

The table below gives an overview for the individual dialog panes descriptions:

Section	Subsection	Manual Page
Configuration	General Settings	19
	Special Function Objects	20
	Object Dictionary	23
	Process Data Objects	26
	PDO Properties	26
	PDO Mapping	29
Device Description	Device	29
	EDS	32

Table 1: Descriptions Dialog Panes

1.1.1 Online Help

The generic CANopen Slave DTM contains an integrated online help facility.

- To open the online help, click on **Help** or press **F1**.

1.1.2 List of Revisions

Index	Date	Version	Component	Chapter	Revisions
7	15-11-17	1.10.x.x, 1.10.x.x	CANopenGenSlaveDTM.dll, COGenericSlaveDt mGui.ocx	3.6.1	Section <i>PDO Properties</i> updated.
8	17-02-22	1.10.x.x, 1.10.x.x	CANopenGenSlaveDTM.dll, COGenericSlaveDt mGui.ocx	1.4.1	Section <i>Requirements</i> Internet access added, Windows 8.1 and Windows 10 added.

Table 2: List of Revisions

1.1.3 Conventions in this Manual

Notes, operation instructions and results of operation steps are marked as follows:

Notes



Important: <important note you must follow to avoid malfunction>



Note: <general note>



<note, where to find further information>

Operation Instructions

1. <instruction>

2. <instruction>

or

➤ <instruction>

Results

↪ <result>

1.2 Legal Notes

Copyright

© Hilscher Gesellschaft für Systemautomation mbH

All rights reserved.

The images, photographs and texts in the accompanying materials (in the form of a user's manual, operator's manual, Statement of Work document and all other document types, support texts, documentation, etc.) are protected by German and international copyright and by international trade and protective provisions. Without the prior written consent, you do not have permission to duplicate them either in full or in part using technical or mechanical methods (print, photocopy or any other method), to edit them using electronic systems or to transfer them. You are not permitted to make changes to copyright notices, markings, trademarks or ownership declarations. Illustrations are provided without taking the patent situation into account. Any company names and product designations provided in this document may be brands or trademarks by the corresponding owner and may be protected under trademark, brand or patent law. Any form of further use shall require the express consent from the relevant owner of the rights.

Important notes

Utmost care was/is given in the preparation of the documentation at hand consisting of a user's manual, operating manual and any other document type and accompanying texts. However, errors cannot be ruled out. Therefore, we cannot assume any guarantee or legal responsibility for erroneous information or liability of any kind. You are hereby made aware that descriptions found in the user's manual, the accompanying texts and the documentation neither represent a guarantee nor any indication on proper use as stipulated in the agreement or a promised attribute. It cannot be ruled out that the user's manual, the accompanying texts and the documentation do not completely match the described attributes, standards or any other data for the delivered product. A warranty or guarantee with respect to the correctness or accuracy of the information is not assumed.

We reserve the right to modify our products and the specifications for such as well as the corresponding documentation in the form of a user's manual, operating manual and/or any other document types and accompanying texts at any time and without notice without being required to notify of said modification. Changes shall be taken into account in future manuals and do not represent an obligation of any kind, in particular there shall be no right to have delivered documents revised. The manual delivered with the product shall apply.

Under no circumstances shall Hilscher Gesellschaft für Systemautomation mbH be liable for direct, indirect, ancillary or subsequent damage, or for any loss of income, which may arise after use of the information contained herein.

Liability disclaimer

The hardware and/or software was created and tested by Hilscher Gesellschaft für Systemautomation mbH with utmost care and is made available as is. No warranty can be assumed for the performance or flawlessness of the hardware and/or software under all application

conditions and scenarios and the work results achieved by the user when using the hardware and/or software. Liability for any damage that may have occurred as a result of using the hardware and/or software or the corresponding documents shall be limited to an event involving willful intent or a grossly negligent violation of a fundamental contractual obligation. However, the right to assert damages due to a violation of a fundamental contractual obligation shall be limited to contract-typical foreseeable damage.

It is hereby expressly agreed upon in particular that any use or utilization of the hardware and/or software in connection with

- Flight control systems in aviation and aerospace;
- Nuclear fusion processes in nuclear power plants;
- Medical devices used for life support and
- Vehicle control systems used in passenger transport

shall be excluded. Use of the hardware and/or software in any of the following areas is strictly prohibited:

- For military purposes or in weaponry;
- For designing, engineering, maintaining or operating nuclear systems;
- In flight safety systems, aviation and flight telecommunications systems;
- In life-support systems;
- In systems in which any malfunction in the hardware and/or software may result in physical injuries or fatalities.

You are hereby made aware that the hardware and/or software was not created for use in hazardous environments, which require fail-safe control mechanisms. Use of the hardware and/or software in this kind of environment shall be at your own risk; any liability for damage or loss due to impermissible use shall be excluded.

Warranty

Hilscher Gesellschaft für Systemautomation mbH hereby guarantees that the software shall run without errors in accordance with the requirements listed in the specifications and that there were no defects on the date of acceptance. The warranty period shall be 12 months commencing as of the date of acceptance or purchase (with express declaration or implied, by customer's conclusive behavior, e.g. putting into operation permanently).

The warranty obligation for equipment (hardware) we produce is 36 months, calculated as of the date of delivery ex works. The aforementioned provisions shall not apply if longer warranty periods are mandatory by law pursuant to Section 438 (1.2) BGB, Section 479 (1) BGB and Section 634a (1) BGB [Bürgerliches Gesetzbuch; German Civil Code] If, despite of all due care taken, the delivered product should have a defect, which already existed at the time of the transfer of risk, it shall be at our discretion to either repair the product or to deliver a replacement product, subject to timely notification of defect.

The warranty obligation shall not apply if the notification of defect is not asserted promptly, if the purchaser or third party has tampered with the products, if the defect is the result of natural wear, was caused by unfavorable operating conditions or is due to violations against our operating regulations or against rules of good electrical engineering

practice, or if our request to return the defective object is not promptly complied with.

Costs of support, maintenance, customization and product care

Please be advised that any subsequent improvement shall only be free of charge if a defect is found. Any form of technical support, maintenance and customization is not a warranty service, but instead shall be charged extra.

Additional guarantees

Although the hardware and software was developed and tested in-depth with greatest care, Hilscher Gesellschaft für Systemautomation mbH shall not assume any guarantee for the suitability thereof for any purpose that was not confirmed in writing. No guarantee can be granted whereby the hardware and software satisfies your requirements, or the use of the hardware and/or software is uninterrupted or the hardware and/or software is fault-free.

It cannot be guaranteed that patents and/or ownership privileges have not been infringed upon or violated or that the products are free from third-party influence. No additional guarantees or promises shall be made as to whether the product is market current, free from deficiency in title, or can be integrated or is usable for specific purposes, unless such guarantees or promises are required under existing law and cannot be restricted.

Confidentiality

The customer hereby expressly acknowledges that this document contains trade secrets, information protected by copyright and other patent and ownership privileges as well as any related rights of Hilscher Gesellschaft für Systemautomation mbH. The customer agrees to treat as confidential all of the information made available to customer by Hilscher Gesellschaft für Systemautomation mbH and rights, which were disclosed by Hilscher Gesellschaft für Systemautomation mbH and that were made accessible as well as the terms and conditions of this agreement itself.

The parties hereby agree to one another that the information that each party receives from the other party respectively is and shall remain the intellectual property of said other party, unless provided for otherwise in a contractual agreement.

The customer must not allow any third party to become knowledgeable of this expertise and shall only provide knowledge thereof to authorized users as appropriate and necessary. Companies associated with the customer shall not be deemed third parties. The customer must obligate authorized users to confidentiality. The customer should only use the confidential information in connection with the performances specified in this agreement.

The customer must not use this confidential information to his own advantage or for his own purposes or rather to the advantage or for the purpose of a third party, nor must it be used for commercial purposes and this confidential information must only be used to the extent provided for in this agreement or otherwise to the extent as expressly authorized by the disclosing party in written form. The customer has the right, subject to the obligation to confidentiality, to disclose the terms and conditions of this agreement directly to his legal and financial consultants as would be required for the customer's normal business operation.

Export provisions

The delivered product (including technical data) is subject to the legal export and/or import laws as well as any associated regulations of various countries, especially such laws applicable in Germany and in the United States. The products / hardware / software must not be exported into such countries for which export is prohibited under US American export control laws and its supplementary provisions. You hereby agree to strictly follow the regulations and to yourself be responsible for observing them. You are hereby made aware that you may be required to obtain governmental approval to export, reexport or import the product.

1.3 Registered Trademarks

Windows® XP, Windows® Vista, Windows® 7, Windows® 8, Windows® 8.1 and Windows® 10 are registered trademarks of Microsoft Corporation.

CANopen® is a registered trademark of CAN in AUTOMATION - International Users and Manufacturers Group e.V (CiA), Nürnberg.

All other mentioned trademarks are property of their respective legal owners.

1.4 About Generic CANopen Slave DTM

You can use the CANopen generic Slave DTM to configure the CANopen Slave devices described with EDS files within a FDT Framework.

The information necessary for the configuration of the CANopen Slave devices is stored within the CANopen Master device when using the CANopen generic Slave DTM and thus the Master device is configured.

1.4.1 Requirements

System Requirements

- PC with 1 GHz processor or higher
- Windows® XP SP3,
Windows® Vista (32 bit) SP2,
Windows® 7 (32 bit und 64-Bit) SP1,
Windows® 8 (32-Bit und 64-Bit),
Windows® 8.1 (32-Bit und 64-Bit),
Windows® 10 (32-Bit und 64-Bit)
- Administrator privilege required for installation
- Internet Explorer 5.5 or higher
- RAM: min. 512 MByte, recommended 1024 MByte
- Graphic resolution: min. 1024 x 768 pixel
- Keyboard and Mouse
- Restriction: Touch screen is not supported.



Note: If the project file is used on another PC,

- the other PC must also comply to these system requirements,
- the device description files of the devices used in the project must be imported to the configuration software SYCON.net on the other PC,
- respectively the DTMs of the devices used in the project must be installed on the other PC.

Requirements CANopen Generic Slave DTM

Requirements for working with the CANopen generic Slave DTM are:

- Installed FDT/DTM V 1.2 compliant frame application
- Installed CANopen Master DTM
- EDS file of the devices to be configured
- The user needs to reload the Device Catalog

Loading EDS files

To add devices to the **netDevice** device catalog, you must import the EDS file of the used device via **netDevice** menu **Network > Import Device Descriptions** into the EDS folder of the DTM. Then the Device Catalogue must be reloaded. The folder EDS inclusively Windows® XP is located in the application data directory (All Users) of the configuration software (or from with Windows® 7 on in the *C:\ProgramData\ SYCONnet* directory).



For further information refer to section *Configuration Steps* on page 15 , under step 1 and 2.

1.5 Dialog Structure of the Generic CANopen Slave DTM

The graphical user interface of the DTM is composed of different areas and elements listed hereafter:

1. A header area containing the **General Device Information**,
2. The **Navigation Area** (area on the left side),
3. The **Dialog Pane** (main area on the right side),
4. **OK, Cancel, Apply, Help**,
5. The **Status Line** containing information e. g. the online-state of the DTM.

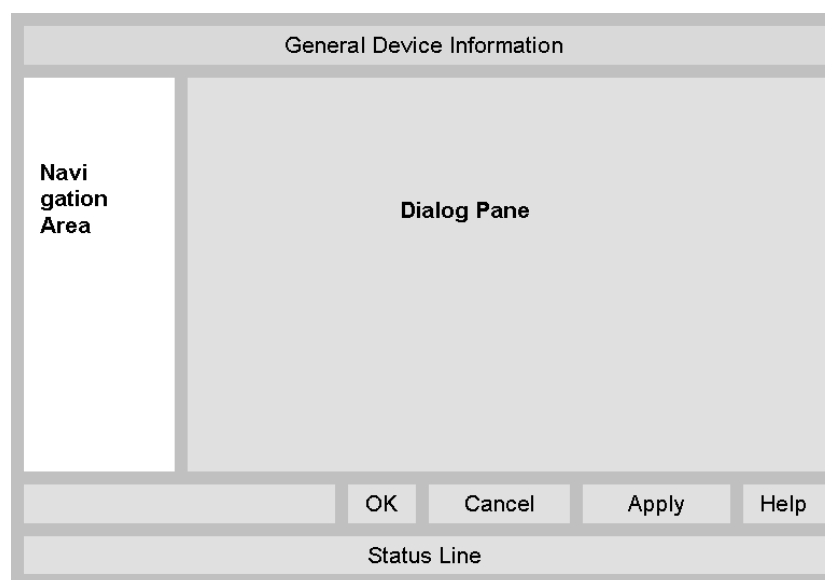


Figure 1: Dialog Structure of the Generic CANopen Slave DTM

1.5.1 General Device Information

Parameter	Meaning
IO Device	Name of the device
Vendor	Vendor name of the device
Device ID	Identification number of the device
Vendor ID	Identification number of the vendor

Table 3: General Device Information

1.5.2 Navigation Area

The **Navigation Area** contains folders and subfolders to open the dialog panes of the DTM.

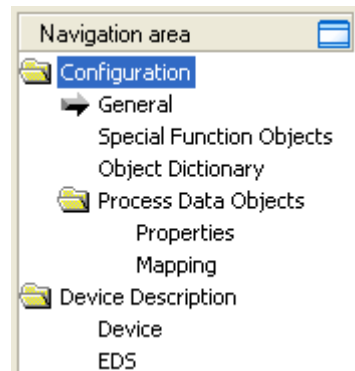




Figure 2: Navigation Area

- Select the required folder and subfolder.
- The corresponding Dialog pane is displayed.

Hide / display Navigation

	Hiding the navigation area (above right side).
 Show navigation area	Opening the navigation area (below left side).

1.5.3 Dialog Panes

At the dialog pane the **Settings** or **Device Description** panes are opened via the corresponding folder in the navigation area.

Configuration	
General	The dialog General Settings displays EDS file data. For further information see section <i>General Settings</i> on page 19.
Special Function Objects	The dialog Special Function Objects displays data of the synchronization, time stamp and emergency message. For further information see section <i>Special Function Objects</i> on page 20.
Object Dictionary	The dialog Object Dictionary represents the object dictionary of the device. The display shows data read out from the EDS file. For further information see section <i>Object Dictionary</i> on page 23.
Process Data Objects	PDO Properties: In the dialog PDO Properties the transmit and the receive PDOs are displayed. For further information see section <i>PDO Properties</i> on page 26
	PDO Mapping: The dialog PDO Mapping permits to map the contents of a PDO. For further information see section <i>PDO Mapping</i> on page 29.
Device Description	
Device	The Device Info pane contains the manufacturer information about the device. For further information see section <i>Device</i> on page 29.
EDS	By use of the EDS Viewer pane an EDS file can be viewed and searched through. For further information see section <i>EDS</i> on page 32.

Table 4: Overview Dialog Panes

1.5.4 OK, Cancel, Apply and Help

OK, Cancel, Apply and Help you can use as described hereafter.

	Meaning
OK	To confirm your latest settings, click OK . All changed values will be applied on the frame application database. <i>The dialog then closes.</i>
Cancel	To cancel your latest changes, click Cancel . Answer to the safety query Configuration data has been changed. Do you want to save the data? by Yes , No or Cancel . Yes: The changes are saved or the changed values are applied on the frame application database. <i>The dialog then closes.</i> No: The changes are <u>not</u> saved or the changed values are not applied on the frame application database. <i>The dialog then closes.</i> Cancel: <i>Back to the DTM.</i>
Apply	To confirm your latest settings, click Apply . All changed values will be applied on the frame application database. <i>The dialog remains opened.</i>
Help	To open the DTM online help, click Help .

Table 5: OK, Cancel, Apply and Help

1.5.5 Table Lines

In the DTM dialog pane table lines can be selected, inserted or deleted.

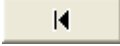


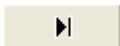

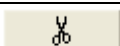
	Meaning
	To select the first line of a table use First Line .
	To select the previous line of a table use Previous Line .
	To select the next line of a table use Next Line .
	To select the last line of a table use Last Line .
	Create a new Line inserts new lines into the table.
	Delete selected Line deletes the selected line from the table.

Table 6: Selecting, inserting, deleting Table Line

1.5.6 Status Bar

The **Status Bar** displays information about the current state of the DTM. The current activity, e.g. the DTM connection state, is signaled graphically via icons in the status bar.

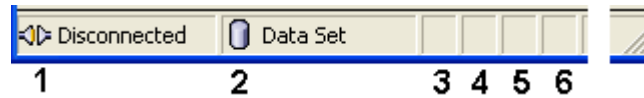


Figure 3: Status Bar – Status Fields 1 to 6






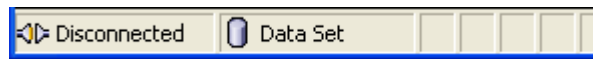
Status Field	Icon / Meaning	
1	DTM Connection States	
		Connected: Icon closed = Device is online
		Disconnected: Icon opened = Device is offline
2	Data Source States	
		Data set: The displayed data are read out from the instance data set (database).
		Device: The displayed data are read out from the device.
3	States of the instance Date Set	
		Valid Modified: Parameter is changed (not equal to data source).

Table 7: Status Bar Icons [1]

Offline State



Online State

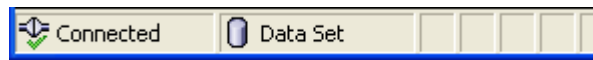


Figure 4: Status Bar Display Example

2 Getting started

2.1 Configuration Steps

The following overview describes the steps to configure a CANopen Slave device with the CANopen generic Slave DTM as it is typical for many cases. At this time it is presupposed that the CANopen Master DTM installation was already done.

The overview lists all the steps in a compressed form. For detailed descriptions of each step refer to the sections noted in the column *For detailed information see section*.

#	Step	Short Description	For detailed information see section	Page
1	Add CANopen Slave in the Device Catalog	Add the Slave in the Device Catalog by importing the device description file to the Device Catalog. Depending of the FDT Container. For netDevice: - Network > Import Device Descriptions.	(See Operating Instruction Manual netDevice and netProject)	-
2	Load device catalog	Depending of the FDT Container: For netDevice: - select Network > Device Catalog , - select button Reload Catalog .	(See Operating Instruction Manual netDevice and netProject)	-
3	Create new project / Open existing project	Depending of the frame application. For the configuration software: - select File > New or File > Open .	(See Operating Instruction Manual of the Frame Application)	-
4	Insert Master or Slave device into configuration	Depending of the FDT Container: For netDevice: - in the Device Catalog click to the Master, - and insert the device via drag and drop to the line in the network view, - in the Device Catalog click to the Slave device, - and insert the device via drag and drop to the Master bus line in the network view.	(See Operating Instruction Manual of the Frame Application)	-
5	Configure Slave device	Configure the Slave device. - Double click to the device icon of the Slave. - The Generic Slave DTM configuration dialog is displayed. In the Generic Slave DTM configuration dialog: - select Configuration > Object Dictionary , - define the object filters, - Select Configuration > Special Function Objects , - select the options for the synchronization, time stamp and emergency message, - select Configuration > Process Data Objects > PDO Properties , - configure the PDO to be used for the communication, - select Configuration > Process Data Objects > PDO Mapping , - configure the list of the mappable or the list of the mapped objects each, - close the Generic Slave DTM configuration dialog via the button OK .	Configuring Device Parameters Object Dictionary Special Function Objects PDO Properties PDO Mapping	18 23 23 26 29
6	Configuration Steps Master device	Configure the Master device via CANopen Master DTM.	(See Operating Instruction Manual DTM for CANopen Master devices)	-

#	Step	Short Description	For detailed information see section	Page
7	Save project	Depending of the frame application. For the configuration software: - select File > Save .	<i>(See Operating Instruction Manual of the Frame Application)</i>	-

Table 8: Getting started - Configuration Steps

3 Configuration

3.1 Overview Configuration

Dialog Panes “Configuration”

The table below gives an overview about the available **Configuration** dialog panes descriptions:

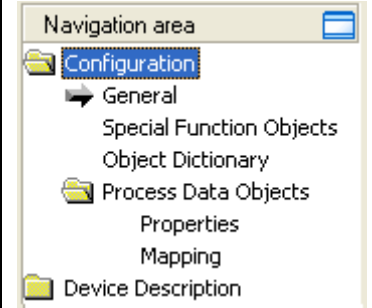
Generic CANopen Slave DTM	Folder Name / Section	Page
	<i>General Settings</i>	19
	<i>Special Function Objects</i>	20
	<i>Object Dictionary</i>	23
	<i>Process Data Objects</i>	26
	<i>PDO Properties</i>	26
	<i>PDO Mapping</i>	29

Table 9: Descriptions of the Dialog Panes Configuration



Notice the descriptions in the section *Configuration Steps* on page 15.



Note: Access to the configuration panes is enabled without requirement of user rights. However for editing certain user rights are required. Further information can be found in section and *User Rights* on page 34.

3.2 Configuring Device Parameters

The following steps are needed to configure the device parameters using the Generic CANopen Slave DTM:

Object Dictionary

1. Define the object filters.
 - Select **Configuration > Object Dictionary** in the navigation area.

Special Function Objects

2. Select the configuration options for the synchronization, time stamp and emergency message.
 - Select **Configuration > Special Function Objects** in the navigation area.
 - Select whether:
 - the CANopen Slave device shall generate the synchronization message,
 - the CANopen Slave device shall consume/produce the time stamp message,
 - the CANopen Master device shall be able to receive the emergency message,
 - and whether for each of these messages the 29-bit CAN-ID of the CAN-ID extended frame shall be valid.

Process Data Objects

3. Configure the PDO.
 - Select **Configuration > Process Data Objects > PDO Properties** in the navigation area.
 - Configure the PDO to be used for the communication.
4. Configure the PDO Mapping.
 - Select **Configuration > Process Data Objects > PDO Mapping** in the navigation area.
 - Configure the list of the mappable or the list of the mapped objects each.

Close Generic Slave DTM Configuration Dialog

5. Click **OK** in order to close the Generic Slave configuration dialog and to store your configuration.

Further Information



For more information refer to section *Object Dictionary* on page 23, *Special Function Objects* on page 23, *PDO Properties* on page 26 and *PDO Mapping* on page 29.

3.3 General Settings

The dialog **General Settings** displays EDS file data:

The screenshot shows the 'General Settings' dialog box. It has a title bar 'General Settings'. Below the title bar, there are several input fields:

- Node ID:** A text box containing the value '2'.
- Device [1000]:** A section header followed by two input fields:
 - Profile:** A text box containing the value '401'.
 - Type:** A text box containing the value '3'.
- Vendor [1008..100A]:** A section header followed by three input fields:
 - Device name:** An empty text box.
 - Hardware version:** A text box containing the value '5/02'.
 - Software version:** A text box containing the value '1.00'.

Figure 5: General Settings

3.3.1 Node ID, Device, Vendor

Parameter	Meaning	Range of Values / Value
Node ID	The Node ID (address) is required to address the device at the bus and must be unique within the CANopen network. Therefore it is not allowed to use this number twice in the same network and must match with the set Node address of the device. Otherwise it is not possible for the Master to build up a communication to this device.	1 ... 127
Device Profile and Device Type	<p>Because of the information of the Device Profile and the Device Type during start of communication, the Master can read out the Object 1000H from the Node and compare it with these data.</p> <p>Each CANopen Node has a mandatory Object 1000H, which must be present in the object directory. This object is named Device Type. The Device Type also includes the information about the Device Profile.</p> <p>The Master reads out the Object 1000H from the Node when starting up the CANopen bus and compares the entries, which are made in the two available fields Device Profile and Device Type. If the Device Profile and the Device Type do not match, the Master reports a parameterization error and does not establish a process data transfer to the Node. The verification can be also deactivated.</p>	Value read out from the EDS file
Device Name, Hard and Software Version	Displayed manufacturer data read out from the EDS file.	Value read out from the EDS file

Table 10: General Settings > Node ID, Device, Vendor

3.4 Special Function Objects

The **Special Function Objects** dialog displays parameter data of the

- **Synchronization Message**,
- **TimeStamp Message**
- and the **Emergency Message**.

The displayed data partly originate from the CANopen specification and can not be edited here. The **SYNC COB-ID** generally can be changed via the CANopen Master DTM. Select here whether:

- the CANopen Slave device shall generate the synchronization message,
- the CANopen Slave device shall consume/produce the time stamp message,
- the CANopen Master device shall be able to receive the emergency message
- and whether for each of these messages the 29-bit CAN-ID of the CAN-ID extended frame shall be valid.

Special Function Objects

Synchronization Message

SYNC COB ID [1005]: ☐ Device generates SYNC message

Communication Cycle Period [1006]: ☐ 29-bit

Synchronous Window Length [1007]:

TimeStamp Message

TIME COB ID [1012]: ☐ Device consumes TIME message

☐ Device produces TIME message

☐ 29-bit

Emergency Message

EMCY COB ID [1014]: ☒ EMCY exists

☐ 29-bit

Figure 6: Special Function Objects

3.4.1 Synchronization Message

Synchronization Message

SYNC COB ID [1005]: ☐ Device generates SYNC message

Communication Cycle Period [1006]: ☐ 29-bit

Synchronous Window Length [1007]:

Figure 7: Special Function Objects - Synchronization Message

Parameter	Meaning	Range of Values / Value
Synchroni- zation Message	A PDO in CANopen can be configured in Event Driven mode or Cyclic Transmission. Both kinds of transmission types can be synchronized to a special synchronization message which is sent by the master in defined time intervals.	
SYNC COB-ID [1005]	The SYNC COB-ID is assigned by the master and cannot be edited here. It can be changed only by the CANopen Master DTM. The SYNC COB-ID specifies the Identifier of the synchronization message. If the Communication Cycle Period is not equal to zero, the transmission of the SYNC message is activated.	Default: 128
	Device generates SYNC message	If checked, the CANopen Slave device generates the synchronization message.
	29-bit	If checked, for this PDO the 29-bit CAN-ID of the CAN-ID extended frame is valid. If not checked, for this PDO the 11-bit CAN-ID is valid.
Communi- cation Cycle Period [1006]	The Communication Cycle Period is assigned by the Master and cannot be edited here. It can be changed only by the CANopen Master DTM. The Communication Cycle Period specifies the time for the interval for the transmission the SYNC message.	
Synchronous Window Length [1007]	The Synchronous Window Length is assigned by the master and cannot be edited here. It can be changed only by the CANopen Master DTM. The Synchronous Window Length specifies the length of the time window for synchronous PDO (process data objects).	

Table 11: Special Function Objects - Synchronization Message

3.4.2 Time Stamp Message

TimeStamp Message

TIME COB ID [1012]: ☐ Device consumes TIME message
☐ Device produces TIME message
☐ 29-bit

Figure 8: Special Function Objects - Time Stamp Message

Parameter	Meaning	Range of Values / Value
Time Stamp Message	For transmission of time data.	
TIME COB-ID [1012]	The TIME COB-ID is assigned by the Master and cannot be edited here. It can be changed only by the CANopen Master DTM. The TIME COB-ID specifies the COB-ID of the time stamp object.	Default: 256
	Device consumes TIME message	Default: Values from EDS file
	Device produces TIME message	
	29-Bit	

Table 12: Special Function Objects - Time Stamp Message

3.4.3 Emergency Message

Emergency Message

EMCY COB ID [1014]: ☒ EMCY exists
☐ 29-bit

Figure 9: Special Function Objects - Emergency Message

Parameter	Meaning	Range of Values / Value
Emergency-Message	Emergency messages are sent by the Node when a node internal event occurs. The CANopen Master can buffer maximally 5 Emergency messages.	
EMCY COB-ID [1014]	The EMCY COB-ID is assigned by the Master and cannot be edited here. It can be changed only by the CANopen Master DTM. The EMCY COB-ID specifies the COB-ID of the Emergency message.	129 ... 255, Default (depends from Node ID): 129 (for Node ID =1), 130 (for Node ID =2), ...
	EMCY exists	Default: Values from EDS file
	29-Bit	

Table 13: Special Function Objects - Emergency Message

3.5 Object Dictionary

The dialog **Object Dictionary** represents the object dictionary of the device. The display shows data read out from the EDS file.

By means of filters in the table **Object Configuration** lists with configured and/or not configured objects can be displayed. A search function allows searching for a special object within the lists.

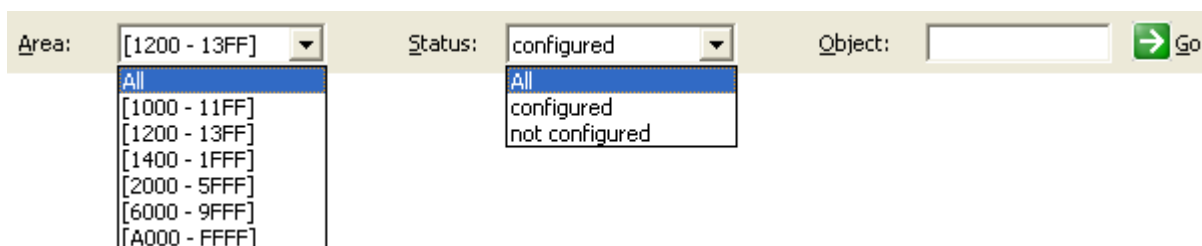


Figure 10: Object Dictionary - Filter Object Configuration

Parameter	Meaning	Range of Values / Value
Area	Via Area a filtered object dictionary area can be selected, which is displayed in the table Object Configuration . If All is selected, in the table Object Configuration all objects are displayed, which are defined in the EDS file.	All, 0x1000 ... 0x11FF, 0x1200 ... 0x 13FF, 0x1400 ... 0x1FFF, 0x2000 ... 0x5FFF, 0x6000 ... 0x9FFF, 0xA000 ... 0xFFFF, Default: All
Status	Via Status it is possible to specify whether in the table Object Configuration all objects, only the configured objects or only the not configured objects of the selected range are to be displayed. Only the objects configured are relevant for data exchange.	All, configured, not configured, Default: All
Object	In the searching field Object the object index and/or the object index and subindex of a certain object can be entered. If the arrow button -> Go is clicked, the searched object (if available) is displayed in the upper line of the table Object Configuration . To enter an object index with subindex a dot is used. Example: 1400.01	Min: 0000 Max: FFFF

Table 14: Object Dictionary - Filter Object Configuration

The objects read out from the EDS file are displayed in the table **Object Configuration**. For better readability for objects with subindex a heading (object index without subindex) is displayed.

Object configuration:















Configure	Index.Subindex	Name	Access
<input type="checkbox"/>	0x1000	Device Type	RO
<input type="checkbox"/>	0x1001	Error Register	RO
<input type="checkbox"/>	0x100B	Node-ID	RO
 <input checked="" type="checkbox"/>	0x100C	Guard Time	RW
 <input checked="" type="checkbox"/>	0x100D	Life Time Factor	RW
 <input checked="" type="checkbox"/>	0x100E	COB-ID Guarding-Protocol	RW
 <input checked="" type="checkbox"/>	0x1014	COB-ID Emergency Message	RW
0x1016 Consumer Heartbeat Time			
<input type="checkbox"/>	0x1016.00	Number of entries	RO
 <input type="checkbox"/>	0x1016.01	Consumer Heartbeat Time 1	RW
 <input type="checkbox"/>	0x1016.02	Consumer Heartbeat Time 2	RW
 <input type="checkbox"/>	0x1016.03	Consumer Heartbeat Time 3	RW
 <input type="checkbox"/>	0x1016.04	Consumer Heartbeat Time 4	RW
 <input type="checkbox"/>	0x1016.05	Consumer Heartbeat Time 5	RW
 <input type="checkbox"/>	0x1016.06	Consumer Heartbeat Time 6	RW
 <input type="checkbox"/>	0x1016.07	Consumer Heartbeat Time 7	RW
 <input type="checkbox"/>	0x1016.08	Consumer Heartbeat Time 8	RW
 <input type="checkbox"/>	0x1016.09	Consumer Heartbeat Time 9	RW
 <input type="checkbox"/>	0x1016.0A	Consumer Heartbeat Time 10	RW

Figure 11: Object Dictionary - Object Configuration

The table **Object Configuration** the following parameter data are provided.




Parameter	Meaning		Range of Values / Value
Configure	The Objects activated in the configuration are checked. The Objects which are not configured are unchecked.		configured (checked), not configured (unchecked)
	Symbol / Checkbox	Description	
		The objects marked with a key symbol can not be enabled or disabled for the configuration in the Object Directory dialog, but they can be added or removed from the configuration elsewhere in the user interface.	
	 <input checked="" type="checkbox"/>	Objects activated in the configuration	configured (checkbox locked)
	 <input type="checkbox"/>	Objects which are <u>not</u> activated in the configuration	<u>not</u> configured (checkbox locked)
	<input checked="" type="checkbox"/>	Objects activated in the configuration	configured
	<input type="checkbox"/>	Objects which are <u>not</u> activated in the configuration	<u>not</u> configured
Index.Sub-index	All objects are addressed in the object index and the corresponding subindex, which are defined by the EDS file.		Object index 0x1000 ... 0xFFFF; Sub index 0x00 ... 0xFF
Name	Symbolic name of the object, which is defined by the EDS file.		From EDS file
Access	Gives the access right of the object, which is defined by the EDS file.		RO = read only (read) RW = read, write (read, write) WO = write only (write) CONST = constant

Table 15: Object Dictionary - Object Configuration

If in the table **Object Configuration** a line is clicked by the cursor, the selected object, the current value, the default value, the data type, the minimum and maximum value are displayed in the fields below the table. By **Display mode** data display can be chosen in decimal or in hexadecimal mode.

Selected object:	01000 Device Type		
Display mode:	Decimal ▼	Data type:	UNSIGNED32
Current value:	0	Min:	0
Default:	0	Max:	4294967295

Figure 12: Object Dictionary - Data selected Object

Parameter	Meaning	Range of Value
Selected Object	In the display field Selected Object the object index, the subindex and the name of the selected object are indicated. These data are defined by the EDS file.	
Display Mode	By selection of the Display Mode decimal and/or hexadecimal from the list field the values are displayed in decimal and/or hexadecimal mode.	Hexadecimal, Decimal, Default: Hexadecimal
Current Value	In the input field Current Value a value can be assigned to the selected object.	
Default, Data Type, Min/Max	In the display fields Default , Data Type and/or Min/Max the default value defined in the EDS file, the data type and/or the minimum and maximum value for the object is indicated. The values Min. and Max. are displayed in decimal mode by default.	

Table 16: Object Dictionary - Data selected Object

3.6 Process Data Objects

3.6.1 PDO Properties

In the dialog **PDO Properties** the transmit and the receive PDOs are displayed. Via **PDO Type** the display can be changed from transmit PDOs (TPDO) to receive PDOs (RPDO) and vice versa.



Figure 13: Process Data Objects > PDO Properties - PDO Type

The PDOs supported by the node are read out of the EDS file and displayed in the table **PDO Configuration**. The PDOs to be used for the communication can be specified i.e. configured in this window.

PDO configuration:

Configure	Index	PDO name
<input checked="" type="checkbox"/>	1400	RxPDO1 parameter
<input checked="" type="checkbox"/>	1401	RxPDO2 parameter
<input checked="" type="checkbox"/>	1402	RxPDO3 parameter
<input checked="" type="checkbox"/>	1403	RxPDO4 parameter
<input type="checkbox"/>	1404	RxPDO5 parameter
<input type="checkbox"/>	1405	RxPDO6 parameter
<input type="checkbox"/>	1406	RxPDO7 parameter
<input type="checkbox"/>	1407	RxPDO8 parameter
<input type="checkbox"/>	1408	RxPDO9 parameter
<input type="checkbox"/>	1409	RxPDO10 parameter
<input type="checkbox"/>	140A	RxPDO11 parameter
<input type="checkbox"/>	140B	RxPDO12 parameter
<input type="checkbox"/>	140C	RxPDO13 parameter
<input type="checkbox"/>	140D	RxPDO14 parameter
<input type="checkbox"/>	140E	RxPDO15 parameter
<input type="checkbox"/>	140F	RxPDO16 parameter
<input type="checkbox"/>	1410	RxPDO17 parameter

Figure 14: Process Data Objects > PDO Properties - PDO Configuration

Parameter	Meaning	Range of Values / Value
PDO Type	Filter function for the table PDO Configuration as - Transmit PDOs - TPDO = Transmit PDO or as - Receive PDOs - RPDO = Receive PDO. Transmit PDOs are sent by the node and are input data of the Master. Receive PDOs are output data of the Master and are received from the node.	TPDO RPDO
Configure	By activating/configuring of a PDO the PDO is used for the communication. The corresponding parameter values are part of the master configuration. During initialization the master transfers these parameters automatically into the node (default behavior). Note: The transmission of the parameters during the initialization phase can also be deactivated and/or become deactivated. I.e., the node uses parameters, which can be different from the parameters set here.	configured (checked), not configured (unchecked)

Parameter	Meaning		Range of Values / Value
	Checkbox	Description	
	<input checked="" type="checkbox"/>	PDOs activated in the configuration The PDO is used for the communication.	configured (checked) (checkbox locked)
	<input checked="" type="checkbox"/>	PDOs activated in the configuration The PDO is used for the communication.	configured (checked)
	<input type="checkbox"/>	PDOs which are <u>not</u> activated in the configuration The PDO is <u>not</u> used for the communication.	<u>not</u> configured (unchecked)
Index	Object Index of the Process data object (PDO)		0x1400 ... 0x15FF 0x1800 ... 0x19FF
PDO Name	Here RxPDO name and/or TxPDO name is indicated. These are defined in the EDS file.		

Table 17: Process Data Objects > PDO Properties - PDO Configuration (examine)

Each process data object (PDO) has characteristics. These are displayed below the table.

COB ID

CAN ID: ☒ PDO exists ☒ RTR allowed ☐ 29-bit

Transmission type:

Transmission rate:

Inhibit time: ms

Event timer: ms

Transmission type:

Figure 15: Process Data Objects > PDO Properties - Data selected Object (Example)

Parameter	Meaning		Range of Values / Value
COB-ID	<p>The COB-ID contains the CAN identifier and additional parameters for the related communication object. According to the CANopen specification ([2] page 131, Table 73) these are the „exists/not exists bit“, the „remote frame support bit“ (RTR allowed) and the „frame format 11 /29 bit“.</p> <p>COB-ID = Communication Object Identifier.</p> <p>The CAN identifier is the main part of the arbitration field of a CAN data frame or CAN remote frame. It comprises 11 bit (base frame format) or 29 bit (extended frame format). The CAN identifier value determines implicitly the priority for the bus arbitration.</p>		0 ... 2047
	PDO exists	If checked, the PDO is selected for the configuration.	Default: Values from EDS file
	RTR allowed	<p>If checked, for this PDO the message-triggering mode “Remotely requested” is allowed, which means that the transmission of an event-driven PDO is initiated on receipt of a RTR initiated by a PDO consumer.</p> <p>If not checked, for this PDO the message-triggering mode “Remotely requested” is not allowed.</p> <p>Note: A RTR is not allowed to inquire for an emergency transmission. [2]</p> <p>RTR = Remote transmission request</p>	

Parameter	Meaning		Range of Values / Value
	29-bit	<p>If checked, for this PDO the 29-bit CAN-ID of the CAN-ID extended frame is valid.</p> <p>If not checked, for this PDO the 11-bit CAN-ID is valid.</p>	
Transmission Type	<p>For the transmit and/or receive PDOs different transmission types are possible. For a PDO in CANopen event driven, synchronous or asynchronous transmission can be configured. Transmission types can be synchronized to the synchronization message SYNC for example, which is sent by the master in defined time intervals.</p> <p>Synchronous means that the transmission of the PDO is related to the SYNC message.</p> <p>Asynchronous means that the transmission of the PDO is not related to the SYNC message and can be done at any time.</p> <p>Note: The support of the different transmission types is manufacturer and device dependent. For CANopen the support of individual and/or all transmission types is not required. Whether a device supports the desired transmission type, must be reread and/or examined in the technical manual of the used device, if necessary.</p>		<p>0 ... 255</p> <p>synchronous acyclic (0) synchronous cyclic (1-240) synchronous RTR (252) asynchronous RTR (253) Event driven, profile specific (254) Event driven, manufacturer specific (255)</p>
Transmission rate	<p>For synchronous TPDOs for the transmission type synchronous cyclic (1-240) another rate is to be set, to which SYNC message the data transmission refers.</p> <p>A Transmission rate of 1 means that the message will be transferred with each SYNC message. A Transmission rate of n means that the message will be transferred with each n-th SYNC message. Asynchronous TPDOs are not transferred in a temporal correlation with a SYNC.</p>		
Inhibit Time	<p>The Inhibit Timer (if supported) describes the time interval, which at least must be waited between the transmissions of two equal messages. Thus a too frequent transmission of the same message is suppressed.</p>		
Event Timer	<p>The Event Timer (if supported) is possible only for TPDO transmission types 254 and 255.</p> <p>The expiration of the timer is used in the node as event, in order to send the TPDO. Manufacturer and/or device-specifically also an application event can activate the sending of the TPDOs and reset the Event Timer.</p>		TPDO 254, 255

Table 18: Process Data Objects > PDO Properties - Data selected Object

3.6.2 PDO Mapping

The dialog **PDO Mapping** permits to map the contents of a PDO.

By use of the **Filter PDO type** field in the table **Mappable Objects** the receive PDOs (RPDO) or alternatively the transmit PDOs (TPDO) can be displayed.

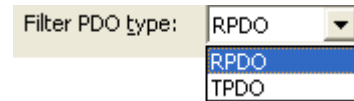


Figure 16: Process Data Objects > PDO Mapping - Filter PDO Type

In the list field **Object Dictionary Area** an object dictionary area can be preselected.

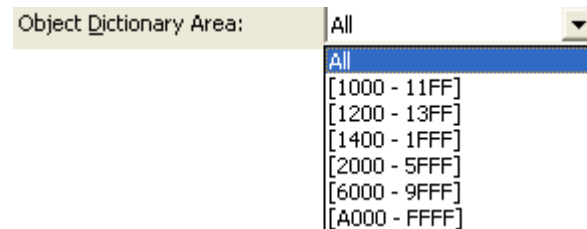


Figure 17: Process Data Objects > PDO Mapping - Object Dictionary Area

The mappable objects appropriate to the preselection are listed in the table **Mappable Objects**.

Mappable objects:					
Index.Subindex	Parameter	Data type	Length	Access	
02200	Digital Byte Outputs				
02200.01	Output Byte 1	UNSIGNED8	8	WO	
02200.02	Output Byte 2	UNSIGNED8	8	WO	
02200.03	Output Byte 3	UNSIGNED8	8	WO	
02200.04	Output Byte 4	UNSIGNED8	8	WO	
02200.05	Output Byte 5	UNSIGNED8	8	WO	
02200.06	Output Byte 6	UNSIGNED8	8	WO	
02200.07	Output Byte 7	UNSIGNED8	8	WO	
02200.08	Output Byte 8	UNSIGNED8	8	WO	
02200.09	Output Byte 9	UNSIGNED8	8	WO	

Figure 18: Process Data Objects > PDO Mapping - Mappable Objects

Parameter	Meaning	Range of Value
Object Dictionary Area	Object dictionary filter range.	All, 0x1000 ... 0x11FF, 0x1200 ... 0x13FF, 0x1400 ... 0x1FFF, 0x2000 ... 0x5FFF, 0x6000 ... 0x9FFF, 0xA000 ... 0xFFFF, Default: All
Mappable Objects	List of the mappable objects.	from EDS file
Index. Subindex	All objects are addressed in the object index and if necessary in the corresponding subindexes, which are defined by the EDS file.	0x1000 ... 0xFFFF as well as 0 ... 0xFF
Parameter	Name of the object from the EDS file.	from EDS file
Data type	Data type of the object from the EDS file respectively according to the data types (Object dictionary data types) listed in the CANopen specification ([2] page 90, Table 44).	from EDS file
Length	The length of the PDOs in bytes.	

Parameter	Meaning	Range of Value
Access	Gives the access rights of the process data objects, which are defined by the EDS file.	rw = read, write

Table 19: Process Data Objects > PDO Mapping - Mappable Objects

In the list field **PDO Contents Mapping for** the PDO is selected, the PDO contents to be displayed.

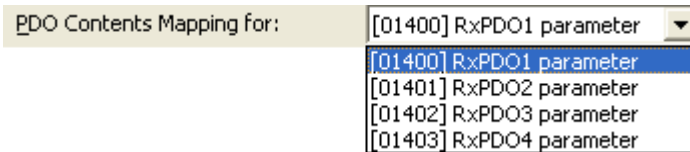


Figure 19: Process Data Objects > PDO Mapping - Filter Mapped Objects

The mapped objects appropriate to the preselection are listed in the table **Mapped Objects**.

Mapped objects:

Index	Subindex	Parameter	Data type	Length
02200	01	Output Byte 1	UNSIGNED8	8
02200	02	Output Byte 2	UNSIGNED8	8
02200	03	Output Byte 3	UNSIGNED8	8
02200	04	Output Byte 4	UNSIGNED8	8
02200	05	Output Byte 5	UNSIGNED8	8
02200	06	Output Byte 6	UNSIGNED8	8
02200	07	Output Byte 7	UNSIGNED8	8
02200	08	Output Byte 8	UNSIGNED8	8

Navigation buttons: up, down, left, right, and a search icon.

Figure 20: Process Data Objects > PDO Mapping - Mapped Objects

Parameter	Meaning	Range of Value
PDO Contents Mapping for	The PDO list field PDO Contents Mapping for contains all configured PDOs of the pane PDO Properties. The objects responsible for data exchange (max. 8 byte/PDO) are assigned to the PDOs.	
Filter PDO Type	The mapping is proceeded separately for the RPDOs and/or the TPDOs.	RPDO TPDO
Mapped Objects	The table Mapped Objects contains only configured objects and always corresponds in the PDO list field PDO Contents Mapping for selected PDOs.	
Index. Subindex	All objects are addressed in the object index and if necessary in the corresponding subindexes, which are defined by the EDS file.	0x1000 ... 0xFFFF as well as 0 ... 0xFF
Parameter	Name of the parameter from the EDS file.	from EDS file
Data type	Data type of the object from the EDS file respectively according to the data types (Object dictionary data types) listed in the CANopen specification ([2] page 90, Table 44).	from EDS file
Length	The Length specifies the length of the PDOs.	

Table 20: Process Data Objects > PDO Mapping - Mapped Objects

To change the object sequence in the table **Mapped Objects** more easily, shifting buttons are available: move completely above, above, down and completely down.

4 Device Description

4.1 Overview Device Description

Descriptions of “Device Description”

The table below gives an overview for the **Device Description** dialog panes descriptions:

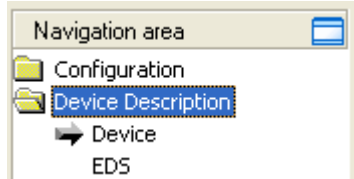
CANopen generic Slave DTM	Folder Name / Section	Page
 Navigation Area - Description	Device	29
	EDS	32

Table 21: Descriptions of the Dialog Panes Device Description

4.2 Device

The **Device Info** dialog contains manufacturer information about the device, which is defined in the EDS file. The following information is indicated:

Parameter	Meaning
Vendor Name	Name of the device manufacturer
Vendor ID	Identification number of the manufacturer
Product name	Name of the device as specified by the manufacturer
Product number	Number of the Device as specified by the manufacturer
Revision number	Hardware reference of the device as specified by the manufacturer
Order Code	Order Code of the device as specified by the manufacturer

Table 22: Device Description > Device

4.3 EDS

The **EDS Viewer** pane shows the content of the EDS file in a text view.

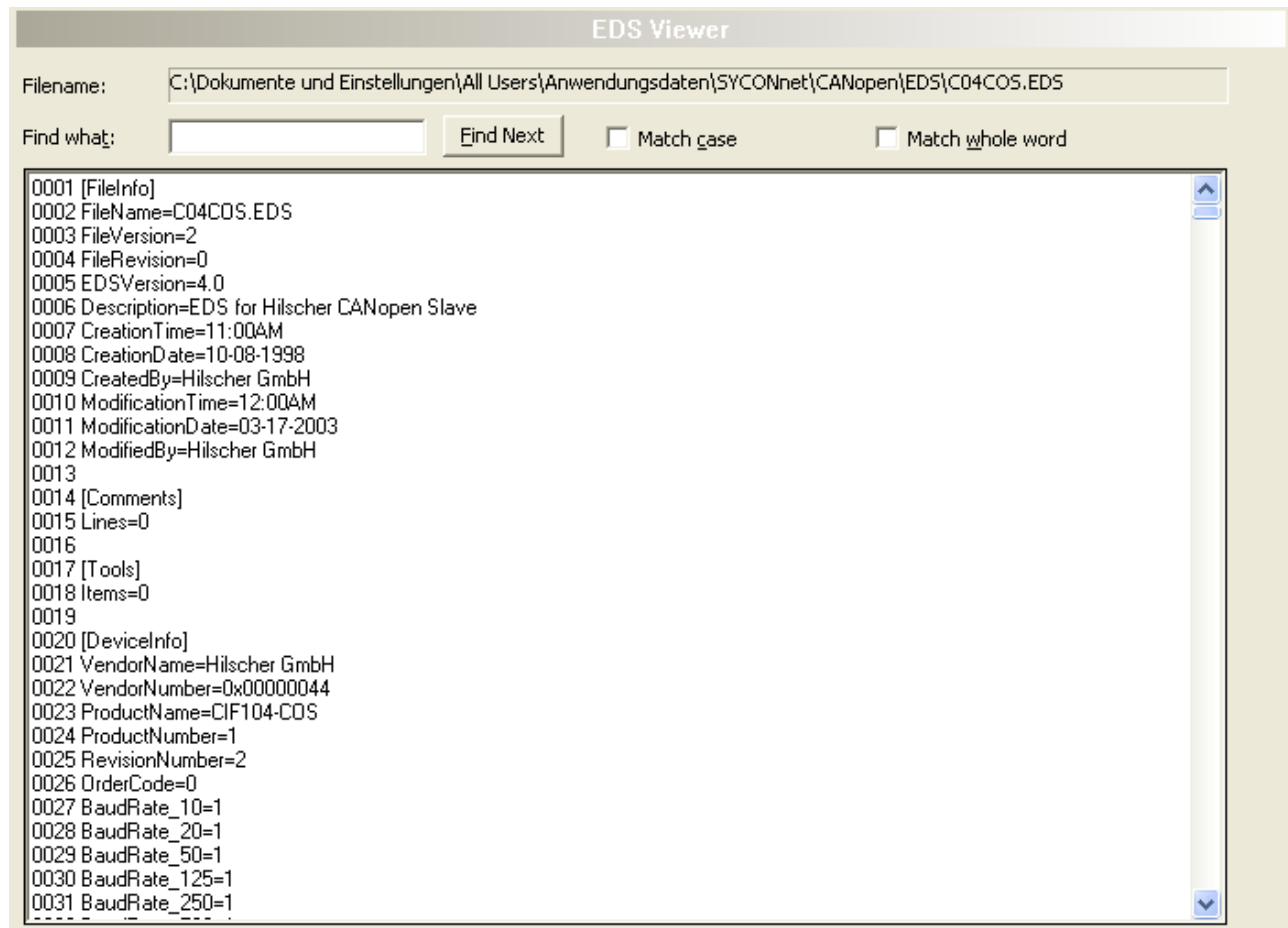


Figure 21: EDS Viewer

Under **Filename** the file directory path and the file name of the displayed EDS file is displayed. **Find what** offers a search feature to search for text contents within the text of the EDS file.

In the **EDS Viewer** pane on the left side, the line number is displayed for simple overview, the further entries show the EDS file in text format.

Parameter	Meaning
Filename	File directory path and the file name of the displayed EDS file.
Find what	Search feature to search for text contents within the text of the EDS file.
Match case	Search option
Match whole word	Search option

Table 23: Device Description - EDS Viewer

5 Appendix

5.1 COB-ID (Predefined Connection Set)

COB-ID stands for communication object identifier. This is the 11 bit covering message identifier of a CAN message. Thereby the upper 4 bits (bit 11 to 8) are the function identifier and the lower 7 bits (bit 7 to bits 0) the bus address of the node.

Broadcast Objects:

Object	Function Code	COB-ID hex	COB-ID dec	Index in the Object Dictionary
NMT	0000	00H	0	-
SYNC	0001	80H	128	1005H, 1006H, 1007H
TIME STAMP	0010	100H	256	1012H, 1013H

Table 24: COB-ID - Broadcast Objects

Peer-to-Peer Objects:

Objects	Function Code	COB-ID hex	COB-ID dec	Index in the Object Dictionary
Emergency	0001	81H-FFH	129-255	1014H, 1015H
PDO 1 (tx)	0011	181H-1FFH	385-511	1800H (1A00H)
PDO 1 (rx)	0100	201H-27FH	513-639	1400H (1600H)
PDO 2 (tx)	0101	281H-2FFH	641-767	1801H (1A01H)
PDO 2 (rx)	0110	301H-37FH	769-895	1401H (1601H)
PDO 3 (tx)	0111	381H-3FFH	897-1023	1802H (1A02H)
PDO 3 (rx)	1000	401H-47FH	1025-1151	1402H (1602H)
PDO 4 (tx)	1001	481H-4FFH	1153-1279	1803H (1A03H)
PDO 4 (rx)	1010	501H-57FH	1281-1407	1403H (1603H)
SDO (tx)	1011	581H-5FFH	1409-1535	1200H
SDO (rx)	1100	601H-67FH	1537-1663	1200H
NMT Error Control	1110	701H-77FH	1793-1919	1016H, 1017H

Table 25: COB-ID - Peer-to-Peer Objects

5.2 User Rights

User-rights are set within the FDT-container. Depending on the level the configuration is accessible by the user or read-only.

To access the **Configuration** and **Device Description** panes of the Generic CANopen Slave DTM you do not need special user rights.



Note: To edit, set or configure the parameters of the **Configuration** panes, you need user rights for *Maintenance*, for *Planning Engineer* or for *Administrator*.

The **Device Description** panes do not contain any editable elements. The indicated values in are only for information purposes.

The following tables give an overview of the user right groups and which user rights you need to configure the single parameters.

5.2.1 Configuration

	Observer	Operator	Maintenance	Planning Engineer	Administrator
<i>General Settings</i>	D	D	X	X	X
<i>Special Function Objects</i>	D (X)	D (X)	X	X	X
<i>Object Dictionary</i>	D (X)	D (X)	X	X	X
<i>Process Data Objects</i>	D (X)	D (X)	X	X	X
<i>PDO Properties</i>	D (X)	D (X)	X	X	X
<i>PDO Mapping</i>	D	D	X	X	X

Table 26: Configuration (D = Displaying, X = Editing, Configuring)

5.3 References

- [1] Device Type Manager (DTM) Style Guide, Version 1.0 ; FDT-JIG - Order No. <0001-0008-000>
- [2] CAN in Automation e.V., Erlangen: CANopen Application Layer and Communication Profile, CiA Draft Standard 301, Version 4.2.0, February 2011
- [3] CANopen Master Protocol API Manual, Revision 14, Hilscher GmbH 2013
- [4] CANopen Slave Protocol API Manual (V3), Revision 4, Hilscher GmbH 2013
- [5] CANdictionary, 6th edition, June 2011, CAN in Automation international users' and manufacturer's group e. V.

5.4 List of Figures

Figure 1: Dialog Structure of the Generic CANopen Slave DTM	11
Figure 2: Navigation Area	12
Figure 3: Status Bar – Status Fields 1 to 6	14
Figure 4: Status Bar Display Example	14
Figure 5: General Settings	19
Figure 6: Special Function Objects	20
Figure 7: Special Function Objects - Synchronization Message	21
Figure 8: Special Function Objects - Time Stamp Message	22
Figure 9: Special Function Objects - Emergency Message	22
Figure 10: Object Dictionary - Filter Object Configuration	23
Figure 11: Object Dictionary - Object Configuration	24
Figure 12: Object Dictionary - Data selected Object	25
Figure 13: Process Data Objects > PDO Properties - PDO Type	26
Figure 14: Process Data Objects > PDO Properties - PDO Configuration	26
Figure 15: Process Data Objects > PDO Properties - Data selected Object (Example)	27
Figure 16: Process Data Objects > PDO Mapping - Filter PDO Type	29
Figure 17: Process Data Objects > PDO Mapping - Object Dictionary Area	29
Figure 18: Process Data Objects > PDO Mapping - Mappable Objects	29
Figure 19: Process Data Objects > PDO Mapping - Filter Mapped Objects	30
Figure 20: Process Data Objects > PDO Mapping - Mapped Objects	30
Figure 21: EDS Viewer	32

5.5 List of Tables

Table 1: Descriptions Dialog Panes	4
Table 2: List of Revisions	5
Table 3: General Device Information	11
Table 4: Overview Dialog Panes	12
Table 5: OK, Cancel, Apply and Help	13
Table 6: Selecting, inserting, deleting Table Line	13
Table 7: Status Bar Icons [1]	14
Table 8: Getting started - Configuration Steps	16
Table 9: Descriptions of the Dialog Panes Configuration	17
Table 10: General Settings > Node ID, Device, Vendor	19
Table 11: Special Function Objects - Synchronization Message	21
Table 12: Special Function Objects - Time Stamp Message	22
Table 13: Special Function Objects - Emergency Message	22
Table 14: Object Dictionary - Filter Object Configuration	23
Table 15: Object Dictionary - Object Configuration	24
Table 16: Object Dictionary - Data selected Object	25
Table 17: Process Data Objects > PDO Properties - PDO Configuration (examine)	27
Table 18: Process Data Objects > PDO Properties - Data selected Object	28
Table 19: Process Data Objects > PDO Mapping - Mappable Objects	30
Table 20: Process Data Objects > PDO Mapping - Mapped Objects	30
Table 21: Descriptions of the Dialog Panes Device Description	31
Table 22: Device Description > Device	31
Table 23: Device Description - EDS Viewer	32
Table 24: COB-ID - Broadcast Objects	33
Table 25: COB-ID - Peer-to-Peer Objects	33
Table 26: Configuration (D = Displaying, X = Editing, Configuring)	34

5.6 Glossary

CAN-ID

The CAN identifier is the main part of the arbitration field of a CAN data frame or CAN remote frame. It comprises 11 bit (base frame format) or 29 bit (extended frame format). The CAN identifier value determines implicitly the priority for the bus arbitration.

COB-ID

Communication Object Identifier.

The COB-ID contains the CAN identifier and additional parameters for the related communication object. According to the CANopen specification ([2] page 131, Table 73) these are the „exists/not exists bit“, the „remote frame support bit“ (RTR allowed) and the „frame format 11 /29 bit“.

DTM

Device Type Manager

The Device Type Manager (DTM) is a software module with graphical user interface for the configuration and/or for diagnosis of devices.

EDS

An Electronic Data Sheet (EDS) provides information necessary to access and alter the configurable parameters of a device. An Electronic Data Sheet (EDS) is an external file that contains information about configurable attributes for the device, including object addresses of each parameter. The application objects in a device represent the destination addresses for configuration data. These addresses are encoded in the EDS.

FDT

Field Device Tool

FDT specifies an interface, in order to be able to use DTM (Device Type Manager) in different applications of different manufacturers.

Master

Master devices initiate the data exchange at the bus.

RTR

Remote transmission request

Node ID

The Node ID is the network address of the device. The network address serves to distinguish itself from other devices on the network. Therefore an unique address must be assigned to each device.

Slave

Slave devices are configured by the Master and perform then the communication.

5.7 Contacts

Headquarters

Germany

Hilscher Gesellschaft für
Systemautomation mbH
Rheinstrasse 15
65795 Hattersheim
Phone: +49 (0) 6190 9907-0
Fax: +49 (0) 6190 9907-50
E-Mail: info@hilscher.com

Support

Phone: +49 (0) 6190 9907-99
E-Mail: de.support@hilscher.com

Subsidiaries

China

Hilscher Systemautomation (Shanghai) Co. Ltd.
200010 Shanghai
Phone: +86 (0) 21-6355-5161
E-Mail: info@hilscher.cn

Support

Phone: +86 (0) 21-6355-5161
E-Mail: cn.support@hilscher.com

France

Hilscher France S.a.r.l.
69500 Bron
Phone: +33 (0) 4 72 37 98 40
E-Mail: info@hilscher.fr

Support

Phone: +33 (0) 4 72 37 98 40
E-Mail: fr.support@hilscher.com

India

Hilscher India Pvt. Ltd.
Pune, Delhi, Mumbai
Phone: +91 8888 750 777
E-Mail: info@hilscher.in

Italy

Hilscher Italia S.r.l.
20090 Vimodrone (MI)
Phone: +39 02 25007068
E-Mail: info@hilscher.it

Support

Phone: +39 02 25007068
E-Mail: it.support@hilscher.com

Japan

Hilscher Japan KK
Tokyo, 160-0022
Phone: +81 (0) 3-5362-0521
E-Mail: info@hilscher.jp

Support

Phone: +81 (0) 3-5362-0521
E-Mail: jp.support@hilscher.com

Korea

Hilscher Korea Inc.
Seongnam, Gyeonggi, 463-400
Phone: +82 (0) 31-789-3715
E-Mail: info@hilscher.kr

Switzerland

Hilscher Swiss GmbH
4500 Solothurn
Phone: +41 (0) 32 623 6633
E-Mail: info@hilscher.ch

Support

Phone: +49 (0) 6190 9907-99
E-Mail: ch.support@hilscher.com

USA

Hilscher North America, Inc.
Lisle, IL 60532
Phone: +1 630-505-5301
E-Mail: info@hilscher.us

Support

Phone: +1 630-505-5301
E-Mail: us.support@hilscher.com